

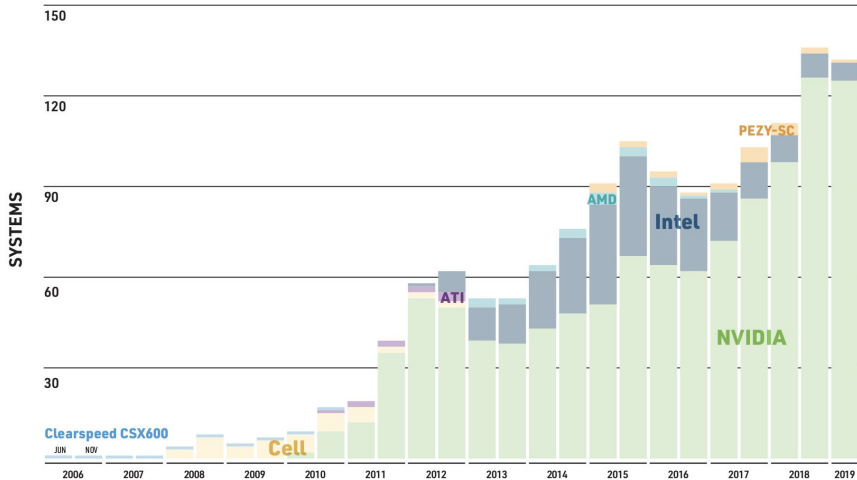
Pace: A Python-Based Implementation of FV3GFS for GPU and CPU Supercomputers

Oliver Elbert, Johann Dahm, Florian Deconinck, Jeremy McGibbon, Tobias Wicky, Elynn Wu, Oliver Fuhrer, Lucas Harris, Rusty Benson

The Future of HPC

- Power constraints lead to increased use of accelerators (GPUs, FPGAs, etc.)
- Architectures are rapidly changing

ACCELERATORS/CO-PROCESSORS



- Climate models will need to adapt to new hardware

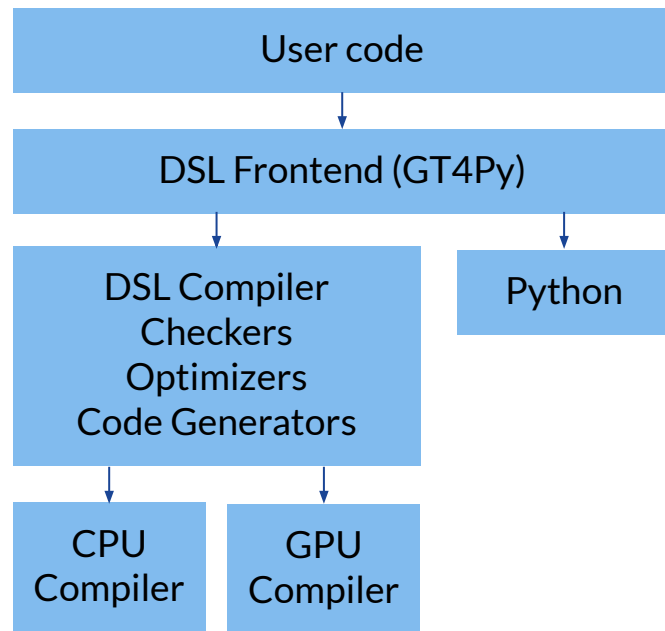
#	System	Nodes	Power [MW]	Rmax [PFlop/s]	Chip Technology
1	Frontier	9,472	21.1	1,102.0	1 x AMD, 4 x 250X
2	Fugaku	158,976	29.9	442.0	1 x A64FX
3	Lumi	2,650*	2.9	151.9	1 x AMD, 4 x 250X*
4	Summit	4,608	10.1	148.6	2 x Power9, 6 x V100
5	Sierra	4,474	7.4	94.6	2 x Power9, 4 x V100
6	TaihuLight	40,960	15.4	93.0	1 x SW26010
7	Perlmutter	1,536	2.5	64.6	1 x AMD, 4 x A100
8	Selene	560	2.6	63.5	2 x AMD, 8 x A100
9	Tianhe-2A	16,000	18.5	61.4	2 x Xeon, 3 x Xeon Phi
10	Adastra	338*	0.92	46.1	1 x AMD, 4 x 250X*

GT4Py: GridTools for Python



- Python has a growing presence in the atmospheric science community
- Python too slow for execution on a supercomputer, but effective as the 'front end' to a DSL that generates efficient code

<https://github.com/GridTools/gt4py>



Motivations

- One codebase for CPU and GPU
- Better optimizations than traditional compiler
- Separate optimization logic from science logic
 - No re-used variables, no 1000-line functions
- Easier to use code base

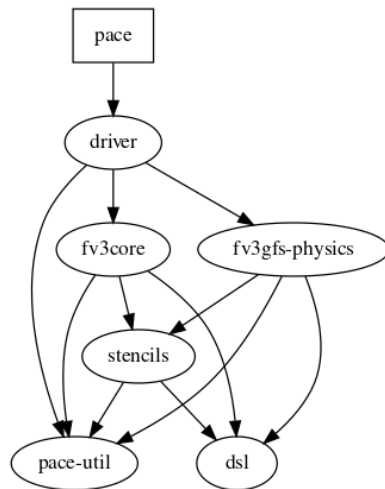


Pace

Fortran



Python



Example Conversion

Fortran

```
subroutine del2_cubed(q, cd, del6_v, del6_u, rarea, grid)

real :: fx(is:ie+1, js:je), fy(is:ie, js:je+1)
!$OMP parallel do default(none) shared(km, q,&
!$OMP is,ie,js,je, & cd) &
!$OMP private(fx, fy)
do k = 1, km
  do j = js, je
    do i = is, ie + 1
      fx(i,j) = del6_v(i,j) * ( q(i-1,j,k) - q(i,j,k) )
    enddo
  enddo

  do j = js, je + 1
    do i = is, ie
      fy(i,j) = del6_u(i,j) * ( q(i,j-1,k) - q(i,j,k) )
    enddo
  enddo

  do j = js, je
    do i = is, ie
      q(i,j,k) = q(i,j,k) + cd * rarea(i,j) * (
        fx(i,j) - fx(i+1,j) + fy(i,j) - fy(i,j+1) )
    enddo
  enddo
enddo
...

end subroutine del2_cubed

call del2_cubed(q, cd, del6_v, del6_u, rarea, grid)
```

Pace

```
@gtscript.function
def delx(q, weight):
    return weight * (q[-1, 0, 0] - q)

@gtscrip.function
def dely(q, weight)
    return weight * (q[0, -1, 0] - q)

@gtscrip.stencil(backend='numpy')
def del2_cubed(q:field, rarea:field, del6_v:field, del6_u:field, cd:float):
    with computation(PARALLEL), interval(...):
        fx = delx(q, del6_v)
        fy = dely(q, del6_u)
        q = q + cd * rarea * (fx - fx[1, 0, 0] + fy - fy[0, 1, 0])

del2_cubed(q, del6_u, del6_v rarea, cd,
          origin=grid.compute_origin(), domain=grid.compute_domain())
```

- Horizontal **loops** removed, **schedule** removed
- Index offsets instead of absolute indices
- No explicit storage statements for **temporary variables**
- Overhead-free, reusable **functions** -- inlining
- Less code
- No explicit parallelism or data storage layout
- Escaping into straight Python is possible

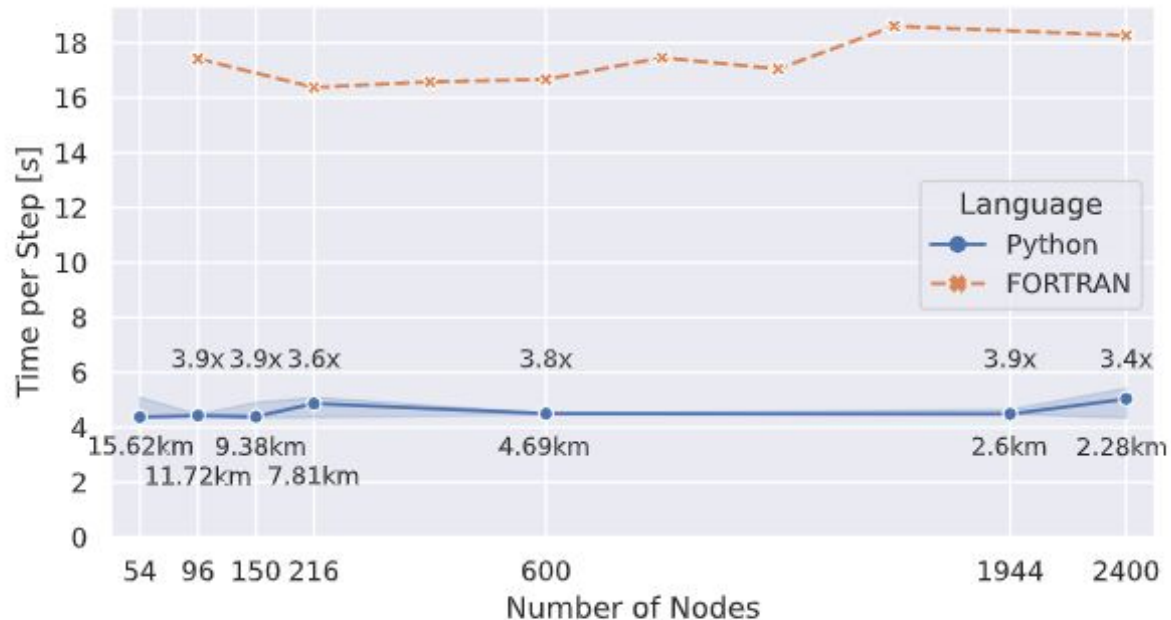
Python Development

Debugging in Python:

- pdb is amazing (built-in to Python)
- Access to Python tooling when debugging
- instead of adding print statements, add plotting or netcdf dumping
- Easy to run and test single module or subtract dycore from itself

```
import pdb; pdb.set_trace()
self._ut_main(
    self._utmp,
    uc,
    v,
    self._cosa_u,
    self._rsin_u,
    utc,
)
import xarray as xr
xr.Dataset(
    data_vars={
        "uc": xr.DataArray(uc),
        "vc": xr.DataArray(v),
        "utc": xr.DataArray(utc),
    },
).to_netcdf("d2a2c_vect_0.nc")
```

Performance



(Submitted as SC'22 paper!)

Benchmark on Piz Daint
supercomputer at CSCS
(Intel Haswell, NVIDIA P100)



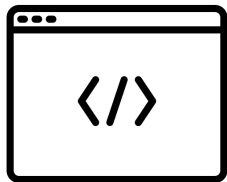
CPU performance still roughly 2x
slower than Fortran

Simulation throughput of
0.12 SYPD at 2.6 km grid spacing

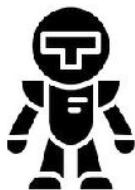
Separation of concerns in action



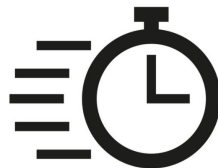
6
weeks of
work



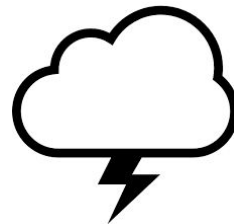
10
performance
code revisions



4
performance
developer



1.8x to 3.5x
speed up
over Fortran

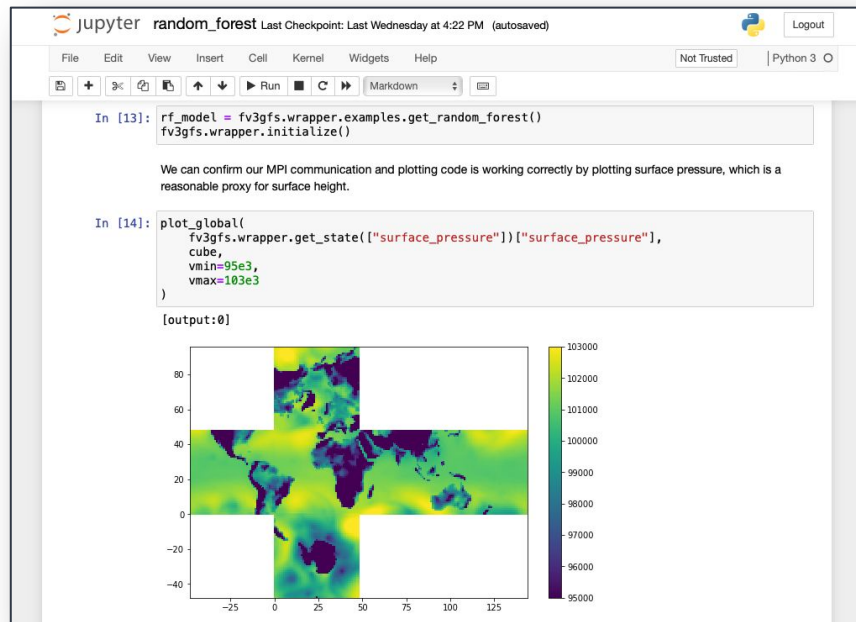


0
model
code revision

Benefits

- Performance
- One codebase for model
- Simple code
- Focus on numerics, not optimization
- Python ecosystem
- Ease of development and debugging
- Public!

<https://github.com/ai2cm/pace>

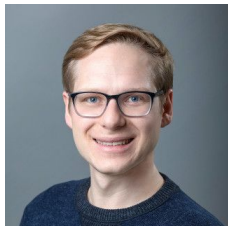


Thanks!

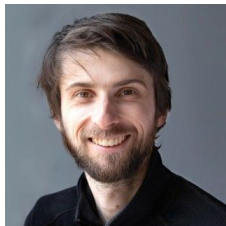
The AI2 DSL Team



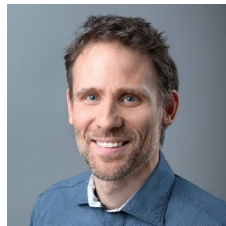
Oliver Elbert



Johann Dahm



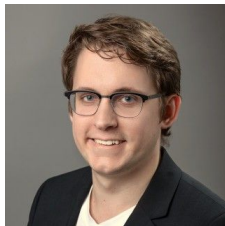
Florian
Deconinck



Oliver Fuhrer



Jeremy
McGibbon

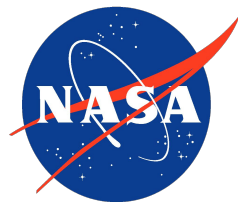


Tobias Wicky



Elynn Wu

Partners



CSCS



MeteoSwiss

ETH zürich



W

UNIVERSITY of
WASHINGTON

AI2

This slide intentionally left blank

Solutions

- Rewrite for backend (e.g. CUDA, AMD-HIP)
 - Multiple hardware-specific codebases
- Compiler Directives
 - Increases code complexity
- How to ‘future proof’ for the next hardware advancement?
- Domain Specific Languages

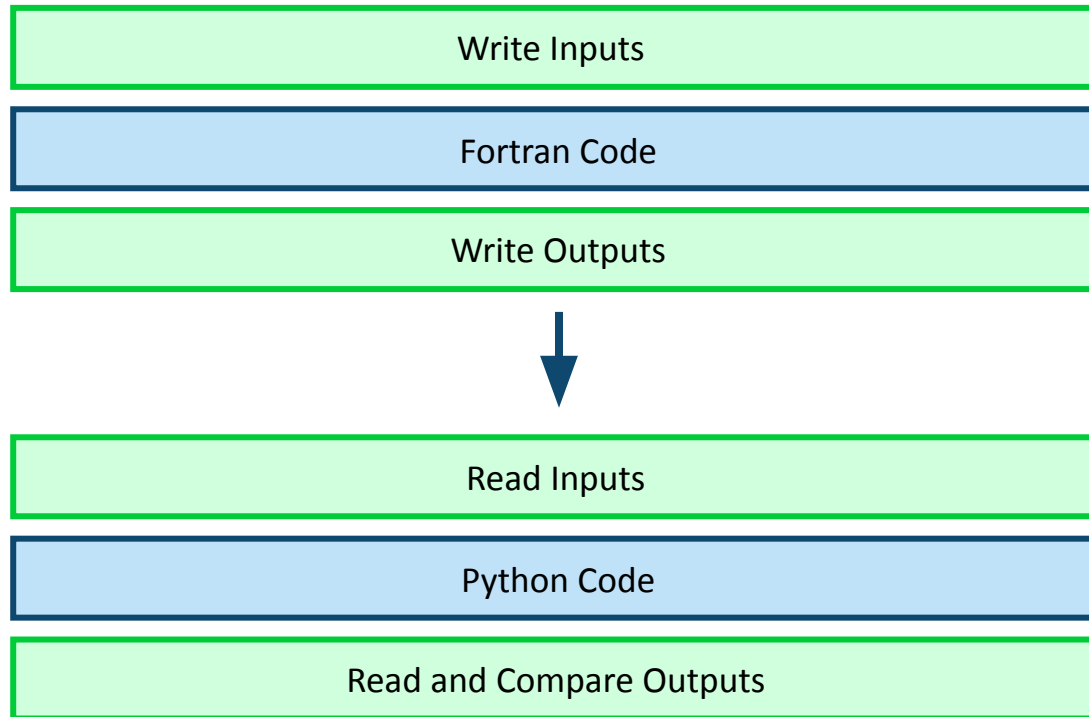
```
!---- Local automatic arrays
!$acc present ( palc,palf,pa2c,pa2f,pa3c,pa3f ) &
!$acc present ( ztu1,ztu2,ztu3,ztu4,ztu5,ztu6,ztu7,ztu8,ztu9 ) &
!---- Module arrays
!$acc present ( cobl,coali,cobti )

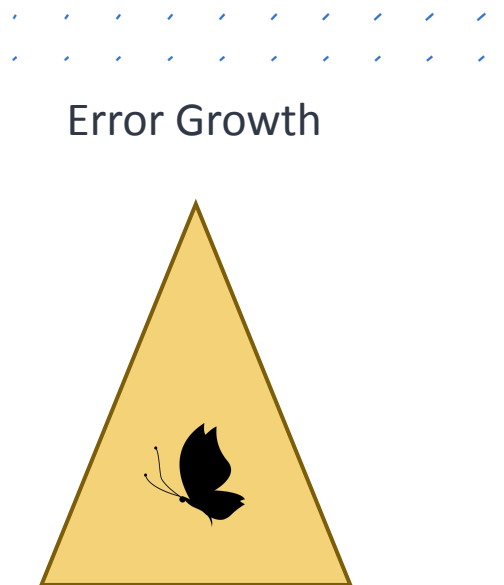
!$acc parallel
!$acc loop gang vector(32) collapse(2)
DO j3 = ki3sc, ki3ec+1
    DO j1 = kilsc, kilec
        pflfd(j1,j3) = pbbr(j1,j3)
        pflcd(j1,j3) = 0.0_dp
    ENDDO
ENDDO
!$acc end parallel

#ifdef _OPENACC
!$acc parallel
!$acc loop gang vector(32)
DO j1 = kilsc, kilec
    CALL coe_th_gpu(pduh2oc(j1,ki3sc), pduh2of(j1,ki3sc), &
        pduco2(j1,ki3sc), pduo3(j1,ki3sc), &
        palogp(j1,ki3sc), palogt(j1,ki3sc), &
        podsc(j1,ki3sc), podsfc(j1,ki3sc), &
        podac(j1,ki3sc), podaf(j1,ki3sc), &
        pbsfc(j1,ki3sc), pbsff(j1,ki3sc), &
        kspec, kh2o, kco2, ko3, &
        palc(j1), palf(j1), pa2c(j1), &
        pa2f(j1), pa3c(j1), pa3f(j1) )

ENDDO
!$acc end parallel
#else
CALL coe_th( pduh2oc,pduh2of,pduco2,pduo3,palogp,palogt, &
    podsc,podsfc,podac,podaf,pbsfc,pbsff, &
    ki3sc,kspec,kh2o,kco2,ko3, &
    kilsc,kiled,ki3sd,ki3ed,kilsc,kilec, &
    ldebug_coe_th,jindex, &
    palc,palf,pa2c,pa2f,pa3c,pa3f)
#endif
```

Testing - Fortran to Python





DYAMOND Project

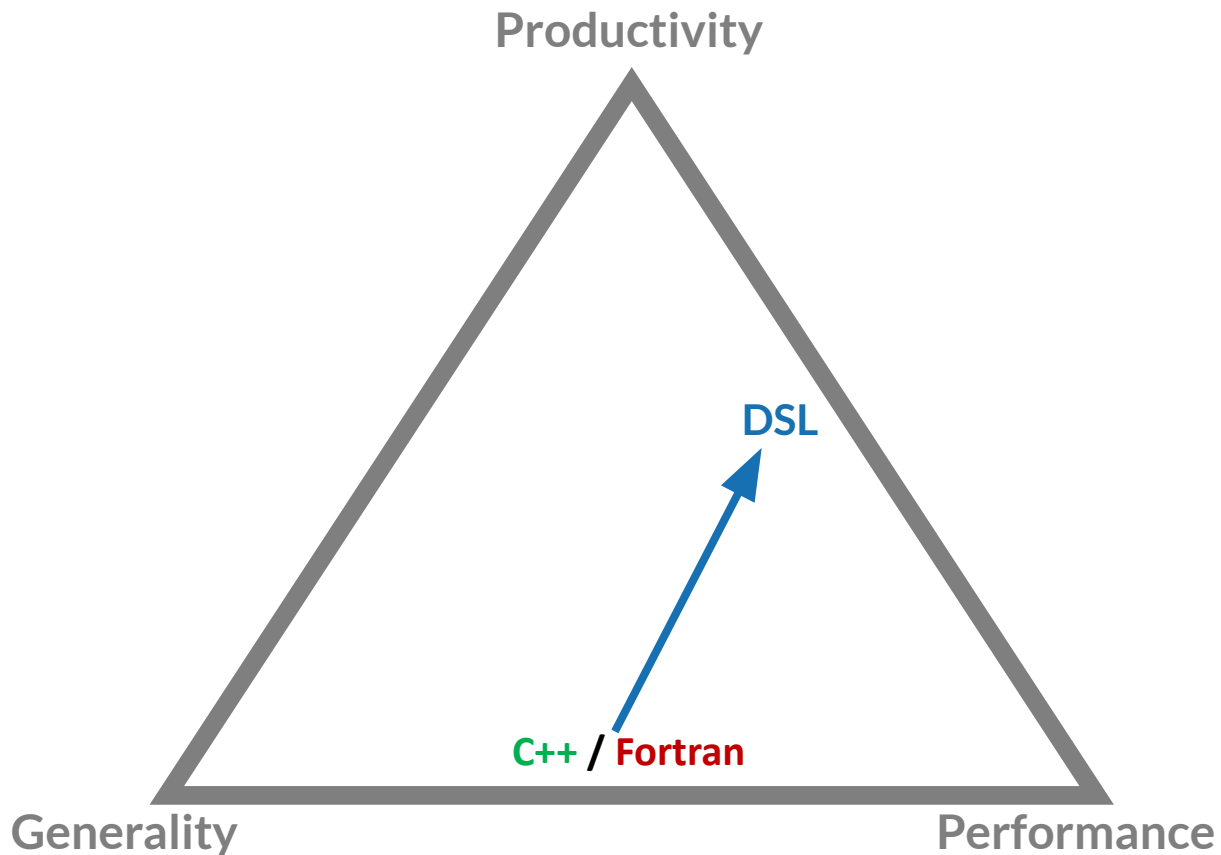
(Sato et al., 2017; Stevens et al., 2019)

adapted from Stevens et al., 2019

***Projected SDPD @ 1km** accounts for horizontal grid size, number of levels, timestep, processor type, missing coupling and assumes ideal scalability onto full UK MetOffice supercomputer (6720 nodes, Cray XC40, Intel Xeon Broadwell, #27)

Model	Grid	Scheme	SDPD	Δt	Nodes	Cores	Processor	SDPD*
ARPEGE-NH	Gaussian red	SI/SL	2.6	100 s	300	7,200	Intel Xeon	1.8
FV3GFS	Cube, C-D	HEVI, split	19	4.5 s	384	13,824	Intel Xeon	9.1
GEOS-5	Cube, C-D	HEVI, split	6.2	3.75 s	512	20,480	Intel Xeon	2.2
ICON	Icosah, C	HEVI, split	6.1	4.5 s	540	12,960	Intel Xeon	4.0
IFS	Octah, spectral	Hydrostatic	124	240 s	360	12,960	Intel Xeon	12
MPAS	Voronoi, C	HEVI, split	3.5	10 s	256	9,216	Intel Xeon	1.1
NICAM	Icosah, A	HEVI, split	2.6	10 s	640	2,560	NEC SX-ACE	-
SAM	Lat-Lon, C	Anelastic	6.0	7.5 s	128	4,608	Intel Xeon	0.013

DSL Approach

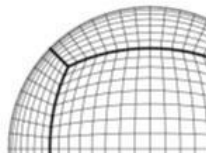


Separation of Concerns

PDEs

$$\nabla^2 u$$

Grid



Discretization

$$\frac{u_{i+1} - 2u_i + u_{i-1}}{\Delta x^2}$$

Implementation

```
for i = 1, ni
  for j = 1, nj
    for k = 1, nk
      u[i+1,j,k] - 2 u[i,j,k] + u[i-1,j,k]
```

Optimization

```
!$acc parallel present(u)
!$acc loop vector collapse(3)
for i = 1, ni
  for j = 1, nj
    for k = 1, nk
      u[i+1,j,k] - 2 u[i,j,k] + u[i-1,j,k]
```

old

new

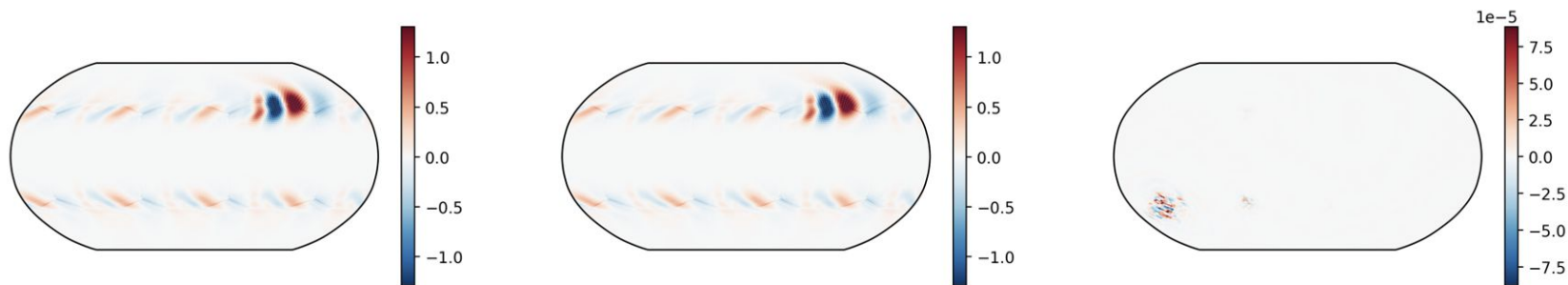
Scientist

Scientist

DSL

Dynamical Core (FV3)

Baroclinic instability testcase (Jablonowski and Williamson 2006)
6 day surface temperature anomaly [K]



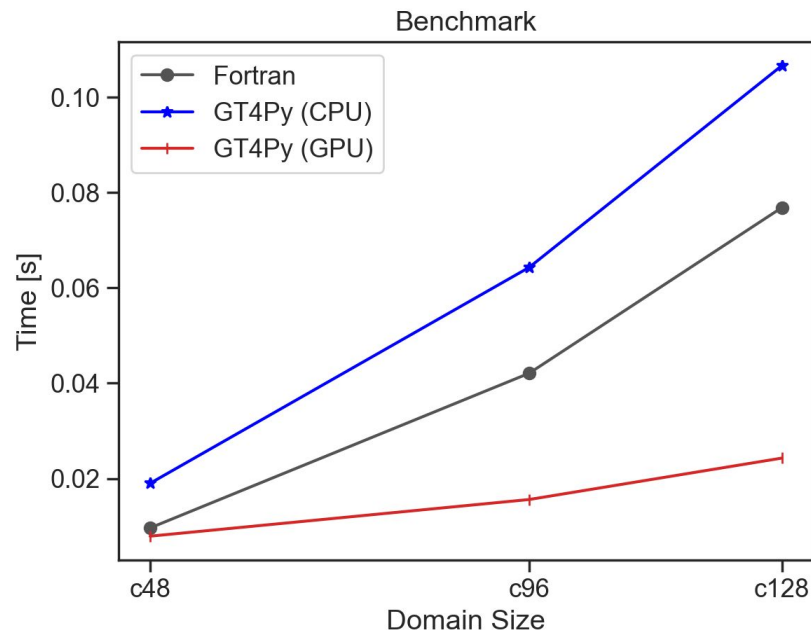
Performance

Also have GFS physics parameterizations ported, encouraging performance

Initial port of Microphysics scheme at c128 (no optimization):

- GPU: 3.2x faster than Fortran
- CPU: 1.4x slower

Again, plenty of speedup on the table



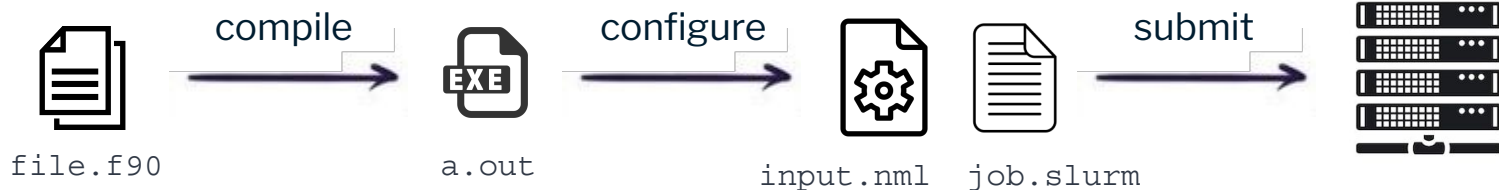
Physical Parameterizations

Check it out on GitHub!
https://github.com/aizcm/physics_standalone

	Microphysics	PBL & Turbulence	Sea-Ice	Shallow Convection	LSM	Radiation
Authors	 Mikael	 Chris	 Vera  Nadja  Nicolai	 Mikael  Chenwei  Langwen	 Safira	 Andrew
Scheme	GFDL Cloud Microphysics Scheme	GFS scale-aware EDMF PBL and Free Atmospheric Turbulence Scheme	GFS Sea Ice Scheme	GFS SAS-based Mass-Flux Scheme for Shallow convection (sa-MF)	GFS Noah Land Surface Model	GFS RRTMG
Status	Ported	Ported	Ported	Ported	Ported	Ported

Just-in-time (JIT) compilation

Fortran



Python DSL

